Aleksander Zgrzywa Kazimierz Choroś Andrzej Siemiński (Eds.)

# Multimedia and Internet Systems: Theory and Practice



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183

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Multimedia and Internet Systems: Theory and Practice



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#### **Preface**

During the last 20 years we have witnessed a rapid development of Multimedia and Network Information Systems. What is even more important, the pace of change does not show any sign of slowing. When we look back we see how many research projects that have originated at universities or in research facilities now are part of our everyday life. This calls for a volume that addresses the capabilities, limitations, current trends and perspectives of Multimedia and Network Information Systems.

Our intention is to offer the readers of this monograph a very broad review of the recent scientific problems in that area. Solving them has became a principal task of numerous scientific teams all over the world. The volume is a selection of representative investigations, solutions and applications submitted by scientific teams working in many European countries.

Content of the book has been divided into four parts:

I Multimedia Information Technology

II Information System Specification

III Information System Applications

IV Web Systems and Network Technologies

Part I contains eight chapters that discusses new methods of visual data processing. The studies and resulting solutions described in the several chapters of this part follow the gaining momentum trend of exploiting artificial intelligence techniques, fuzzy logic, multi-agent approaches in the domain of multimedia information technology. The domain covers image alignment, video deinterlacing, cartographic representation, visual objects description, large scale 3D reconstruction, and hand gesture recognition. Two of the chapters focus on the content-based indexing and retrieval of visual data.

The second part of the book consists of seven chapters. Two of them address the specific problems of different applications of ontology's in information systems and the ontology alignment. This part also contains reports on the experiments on the evaluation of re-sampling combined with clustering and random oracle using genetic fuzzy systems and the study of parameter selection for the Dynamic Travelling Salesman Problem. One of the chapters deals with the modeling failures of

VI Preface

distributed systems in stochastic process algebras. The important from a practical point of view problem of tracking changes in database schemas is also discussed in the last chapter of this part.

Part III presents a handful of applications. It consists of four chapters. One of them describes an adaptive e-learning application with a catchy name of Power Chalk. Innovative solutions to the problem of unified user identification for mobile environments and smart communications for remote users are also discussed. The last chapter presents a rule based expert system that covers semantic matching, spatiotemporal relation operators, and comparison of GIS data to eliminate VAT-carousel crimes.

Part IV refers to the trends and perspectives in Web Systems and Network Technologies. It contains 6 chapters. Two of them deal with e-commerce issues discussing the evaluation of the server performance and presenting an approach to use product reviews from e-commerce websites for the product feature opinion mining task. The usefulness of Web pages can considerably suffer from poor readability. Therefore a special chapter is devoted to a methodology of creating a computer aided system for measuring text readability. Finding relevant services from a service collection is yet another important aspect of the Web Technologies. Two of the chapters in this part are devoted to the problem.

The book should be of great interest to researchers involved in all aspects of multimedia and Internet applications. We hope that it will fulfill the expectations of its readers and we will be also very pleased if the book will attract more scholars to work on the area and to inspire the research community already working on the domain. If so, the goal that motivated authors, reviewers, and editors will be achieved. It will be also the greatest prize for our joint efforts.

Aleksander Zgrzywa Kazimierz Choroś Andrzej Siemiński

### **Contents**

#### Part I: Multimedia Information Technology

1	Fuz	zy Rule-Based Classifier for Content-Based Image Retrieval	3
	Tatio	una Jaworska	
	1.1	Introduction	3
	1.2	Fuzziness	5
		1.2.1 Fuzzy Sets	5
		1.2.2 Fuzzy Rule-Based Classifiers	5
	1.3	Graphical Data Representation	7
	1.4	Classification Results	8
	1.5	Further Use of Classified Objects in CBIR	11
	1.6	Conclusions	11
	Refe	erences	12
2	Dec	entralized Multi-Agent Algorithm for Translational 2D	
		ge Alignment	15
	Tome	áš Machálek, Kamila Olševičová	
	2.1	Introduction	15
	2.2	Problem Statement	17
	2.3	Proposed Solution	17
	2.4	Estimation of Computational Complexity	21
	2.5	Experiments	21
	2.6	Conclusions	23
	Refe	erences	24
3	A S	parse Reconstruction Approach to Video Deinterlacing	25
	Mari	ia Trocan	
	3.1	Introduction	25
	3.2	Background	27
	3.3	Proposed Method	28
	3.4	Experimental Results	30
	3.5	Conclusion	32
	Refe	erences	32

VIII Contents

	Cartographic Representation of Route Reconstruction Results in Video Surveillance System			
	eo Surveillance System			
	ol Lisowski, Andrzej Czyżewski			
4.1	Introduction			
4.2	Related Work			
4.3	Proposed Method			
	4.3.1 Topology of Camera Network			
	4.3.2 Obtaining Contextual Data			
	4.3.3 Architecture of the System			
	4.3.4 Augmenting Cartographic Data			
4.4	Results			
4.5				
Ref	erences			
	ual Objects Description for Their Re-identification in			
	lti-Camera Systems			
	nian Ellwart, Andrzej Czyżewski			
5.1	Introduction			
5.2	Object Tracking			
	5.2.1 Single Camera Object Tracking			
	5.2.2 Multi-Camera Object Tracking			
5.3	Object Description Methods			
5.4	•			
	5.4.1 Dataset Preparation			
	5.4.2 Feature Evaluation			
5.5	Summary			
Ref	erences			
	Compact Descriptor for Video Sequence Matching in the Context			
	of Large Scale 3D Reconstruction			
	nan Parys, Florian Liefers, Andreas Schilling			
6.1				
6.2	Related Work			
6.3	Compact Descriptor and Matching			
	6.3.1 Computation of Compact Descriptor			
	6.3.2 Computation of Similarity Measure			
	6.3.3 Computation of Image Occurrence Statistics			
	6.3.4 Computation of Matching Frames			
6.4	Results			
6.5	Conclusions and Future Work			
Ref	erences			
Hea	adlines Usefulness for Content-Based Indexing of TV Sports			
	vs			
	imierz Choroś			
7.1	Introduction			

Contents IX

	<ul> <li>7.2 Related Works</li> <li>7.3 Book Structure vs. TV Sports News Structure</li> <li>7.4 AVI - Automatic Video Indexer</li> <li>7.5 Structure of TV Sports News</li> <li>7.6 Headlines in TV Sports News</li> <li>7.7 Final Conclusions and Further Studies</li> <li>References</li> </ul>	67 67 70 70 72 74 75
8	<b>Examining Classifiers Applied to Static Hand Gesture</b>	
	Recognition in Novel Sound Mixing System	77
	Michal Lech, Bozena Kostek, Andrzej Czyżewski	77
	8.1 Introduction	77 78
	<ul><li>8.2 System Overview</li></ul>	80
	8.3.1 Tests	80
	8.3.2 Results	81
	8.4 Conclusions	85
	References	85
Par	t II: Information Systems Specification	
9	Multiple Data Tables Processing via One-Sided Concept Lattices	89
	Peter Butka, Jozef Pócs, Jana Pócsová, Martin Sarnovský	0,
	9.1 Introduction	89
	9.2 Preliminaries on One-Sided Concept Lattices	90
	9.3 Closure Operator Defined by Multiple Data Tables	93
	9.4 Conclusions	97
	References	98
10	A Multi-attribute and Logic-Based Framework of Ontology	
	Alignment	99
	Marcin Pietranik, Ngoc Thanh Nguyen	
	10.1 Introduction	99
	10.2 Basic Notions    10.3 Attribute-Based Concept Alignment	101 102
	10.4 Related Works	102
	10.5 Evaluation Methodology	103
	10.6 Summary and Future Works	107
	References	108
11	Application of an Ontology-Based Model to a Wide-Class	
	Fraudulent Disbursement Economic Crimes	109
	Czesław Jędrzejek, Jarosław Bąk 11.1 Introduction	109
	11.2 The Model	111
	11.3 Set of Rules	113

X Contents

	11.4 Queries	116
	11.5 Conclusions	116
	References	117
12	Modelling Failures of Distributed Systems in Stochastic Process	
	Algebras	119
	Jerzy Brzeziński, Dariusz Dwornikowski	11)
	12.1 Introduction	119
	12.2 Basic Definitions	121
	12.2.1 Stochastic Process Algebras	121
	12.2.2 Basic Failures in Distributed Systems	121
	12.3 Modelling Failures	122
	12.3.1 Crash-Recovery Failures	123
	12.3.2 Crash-Stop Failure Models	124
	12.3.3 Omission Model	126
	12.3.4 Modelling Failure Detectors	127
	12.4 Conclusions	128
	References	129
13	<b>Experimental Evaluation of Resampling Combined with</b>	
	Clustering and Random Oracle Using Genetic Fuzzy Systems	131
	Tadeusz Lasota, Zbigniew Telec, Bogdan Trawiński, Grzegorz Trawiński	
	13.1 Introduction	131
	13.2 Methods Used in Experiments	133
	13.3 Experimental Setup	136
	13.4 Experimental Results	137
	13.5 Conclusions	140
	References	141
14	Ant Colony Optimization Parameter Evaluation	143
	Andrzej Siemiński	
	14.1 Introduction	143
	14.2 Basic ACO Algorithm for Static TSP	144
	14.2.1 ACO Basic Operations	145
	14.2.2 Parameter Selection	146
	14.3 Dynamic TSP	146
	14.3.1 Related Work	147
	14.3.2 Graph Generators	147
	14.4 Experiment	149
	14.4.1 Data Exploration	150
	14.4.2 Correlation Analysis	151
	14.5 Conclusions	152
	References	153

Contents XI

15	Tracking Changes in Database Schemas	155
	Jakub Marciniak, Tadeusz Pankowski	
	15.1 Introduction	155
	15.2 Changes Discovering Process	156
	15.2.1 Schemas Similarity	157
	15.2.2 Rule Based Schema Matching	158
	15.2.3 Edit Distance	160
	15.2.4 Transforming Operations	161
	15.3 Conclusions	164
	References	164
Par	rt III: Information Systems Applications	
16	Smart Communication Adviser for Remote Users	169
10	Miroslav Behan, Ondrej Krejcar	10)
	16.1 Introduction	169
	16.2 Problem Definition	170
		173
	16.3 Solution Design	174
	16.4 Application Prototype	
	16.5 Conclusions	176 177
	References	1//
17	PowerChalk: An Adaptive e-Learning Application	179
	Dan-El Neil Vila Rosado, Margarita Esponda-Argüero, Raúl Rojas	
	17.1 Introduction	179
	17.2 ISDT and Related Work	180
	17.3 PowerChalk Structure	182
	17.4 PowerChalk Modules	183
	17.4.1 Main Editor Module	183
	17.4.2 Pen and Digitizer Tablets Module	184
	17.4.3 Multi-screen Manager Module	184
	17.4.4 Handwriting Recognition Module	185
	17.4.5 Communication Module	185
	17.4.6 Collaboration Modules	186
	17.4.7 Magic Panels	187
	17.4.8 Macros Module	187
	17.5 Conclusions and Future Work	187
	References	188
10	Idea Chair Chairman Ann an Line Chairman	
18	Identifying Fraudulent Shipments through Matching Shipping Documents with Phone Records	190
	Czesław Jędrzejek, Maciej Nowak, Maciej Falkowski	189
	18.1 Introduction	189
	18.2 A Model of Data Correlation between Invoices, CMR	10)
	Documents and Driver's Phone Records	191
	18.3 A Route Verification Algorithm	192

XII Contents

	18.4 Results for the GARO Case	195
	18.5 Conclusions and Future Work	197
	References	198
4.0		
19	Open Personal Identity as a Service	199
	Miroslav Behan, Ondrej Krejcar	100
	19.1 Introduction	199
	19.2 Problem Definitions	200
	19.3 Related Works	201
	19.4 Solution Design	202
	19.5 Implementation	204
	19.6 Conclusions	206
	References	206
Par	rt IV: Web Systems and Network Technologies	
20	The Computer-Aided Estimate of the Text Readability	
20	on the Web Pages	211
	Radosław Bednarski, Maria Pietruszka	211
	20.1 Introduction	211
	20.2 Typographical Text Parameters	212
	20.3 Coloured Text on the Screen	213
	20.4 Computer-Aided System for Assessing the Readability of the	214
	Text and the Selection of Its Parameters	214
	20.5 Tests of the System	217
	20.6 Conclusions	219
	References	220
21	MSALSA - A Method of Positioning Search Results in Music	
	Information Retrieval Systems	221
	Zygmunt Mazur, Konrad Wiklak	
	21.1 Introduction	221
	21.2 Description of the MSALSA Algorithm	223
	21.3 Tests Results	225
	21.4 Conclusions	228
	References	228
22	The Concept of Parametric Index for Ranked Web Service	
	Retrieval	229
	Adam Czyszczoń, Aleksander Zgrzywa	
	22.1 Introduction	229
	22.2 Related Work	230
	22.3 Web Service Structure	230
	22.4 Web Service Ranking with Vector Space Model	231
	22.4.1 Relevance Measure	232

Contents	XII
----------	-----

	22.5 Parametric Index 22.5.1 Component Concepts 22.5.2 Merged Weight Vector 22.5.3 Index Structure 22.5.4 Indexing Algorithm 22.6 Experimental Results 22.7 Conclusions and Future Work References	233 234 234 234 236 238
23	Web-Based User Interface for SOA Systems Enhanced	
	by Ontology	239
	Marek Kopel, Janusz Sobecki	
	23.1 Introduction	239
		240
	23.3 User Interface for SOA Systems	241
	23.4 Application of Ontology Enhanced User Interface for	
	SOA Systems	242
	23.4.1 Extending WSDL	245
	23.5 Discussion and Future Works	246
	References	246
24	24.3 Simulation Results 24.3.1 Analysis of System Performance Metrics 24.3.2 Analysis of Business-Oriented Metrics 24.4 Concluding Remarks References	249 249 250 252 253 255 257 258
25	Domain Dependent Product Feature and Opinion Extraction	261
	Based on E-Commerce Websites	261
	Bartomiej Twardowski, Piotr Gawrysiak 25.1 Introduction	261
	25.2 Related Research	
	25.3 Proposed Approach	263
	25.3.1 Data Acquisition	263
	25.3.2 Data Corpus Preparation	264
	25.3.3 Model Training	267
	25.4 Experiment and Results	268
	25.5 Conclusions and Feature Work	269
	References	270
Aut	hor Index	271

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## Part I Multimedia Information Technology

# **Chapter 1 Fuzzy Rule-Based Classifier for Content-Based Image Retrieval**

Tatiana Jaworska

**Abstract.** At present a great deal of research is being done in different aspects of Content-Based Image Retrieval System (CBIR). Thus, it is necessary to develop appropriate information systems to efficiently manage datasets. Image classification is one of the most important services in image retrieval that must support these systems. The primary issue we have addressed is: how can the fuzzy set theory be used to handle crisp data for images. We propose how to introduce fuzzy rule-based classification for image objects. To achieve this goal we have constructed fuzzy rule-based classifiers, taking into account crisp data. In this chapter we present the results of the use of this fuzzy rule-based system in our CBIR.

#### 1.1 Introduction

In recent years, the availability of image resources on the WWW and large image datasets has increased tremendously. This has created a demand for effective and flexible techniques for automatic image classification and retrieval. Although attempts to perform the Content-Based Image Retrieval (CBIR) in an efficient way have been made before, a major problem in this area has been computer perception, to which it is hard to introduce an additional semantic data model. In other words, there is a necessity to introduce fuzzy information models into image retrieval, based on high-level semantic concepts that perceive an image as a complex whole.

Images and graphical data are complex in terms of visual and semantic contents. Depending on the application, images are modelled and indexed using their

- visual properties (or a set of relevant visual features),
- semantic properties,
- spatial or temporal relationships of graphical objects.

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4 T. Jaworska

Over the last decade a number of concepts of the CBIR [1], [2], [3], [4], have been used. Proposals can be found for the relational [5], object-oriented [6], [7] databases. For about 10 years the fuzzy proposition has been applied in object-relation database models [8], [9]. Zadeh's fuzzy sets theory has allowed us to develop limited programming tools, concerned with graphical applications and dealing with imperfect pictorial data. Within the scope of semantic properties, as well as graphical object properties, the first successful attempt was made by Candan and Li [10], who constructed the Semantic and Cognition-based Image Retrieval (SEMCOG) query processor to search for images by predicting their semantic and spatial imperfection.

The feature vector is used for tentative object classification at the local level of a separated object. First, we have to classify objects in order to assign them to a particular class which is later used to describe spatial relationships characteristic of a particular image. In our system spatial object location in an image is used as the global feature; then it supports full identification of graphical elements based on rules of location. Next, classified objects are used to enable the user to compose their own image in the GUI. Finally, we apply classes in order to compare objects coming from different images [21].

We have chosen a fuzzy rule-based classification to support our pattern library which is constructed to enable the user to build their image query in as natural a way as possible. 'Natural' here means handling such objects as houses, trees, water instead of a red square, blue rectangle, etc.

In this chapter we present the fuzzy rule-based classifiers for object classification which takes into account object features, together with different spatial location of segmented objects in the image. In order to improve the comparison of two images, we need to label these objects in a semantic way.

In general, our system consists of four main blocks:

- 1. the image preprocessing block (responsible for image segmentation), applied in Matlab, cf. [11];
- 2. the Oracle Database, storing information about whole images, their segments (here referred to as graphical objects), segment attributes, object location, pattern types and object identification, cf. [12];
- 3. the search engine responsible for the searching procedure and retrieval process based on feature vectors for objects and spatial relationship of these objects in an image, applied in Matlab;
- 4. the graphical user's interface (GUI) allows users to compose their own image, consisting of separate graphical objects as a query. Classification helps in the transition from rough graphical objects to human semantic elements. We have had to create a user-friendly semantic system, also applied in Matlab.

There have been several attempts to design efficient, invariant, flexible and intelligent image archival and retrieval systems based on the perception of spatial relationships. Chang [13] proposed a symbolic indexing approach, called the nine directional lower triangular (9DLT) matrix to encode symbolic images. Using the concept of 9DLT matrix, Chang and Wu [14] proposed an exact match of the retrieval scheme, based upon principal component analysis (PCA). Unfortunately, it transpired that the first principal component vectors (PCVs) associated with the

image and the same image rotated are not the same. Eventually, an invariant scheme for retrieval of symbolic images based upon the PCA was prepared by Guru and Punitha [15].

#### 1.2 Fuzziness

#### 1.2.1 Fuzzy Sets

Let  $T = \{t_1, ..., t_n\}$  be a set of objects, where  $t_i \neq t_j$ , the attributes of  $t_i$  and  $t_j$  are different. Let  $U = \{A_1, ..., A_m\}$  be the set of attributes over  $t_1, ..., t_n$ . Each attribute  $A_i$  has been associated with a domain, denoted by  $U(A_i)$ . The value of attribute  $A_i$  is either a crisp or fuzzy value. According to Zadeh [16], a fuzzy set F in  $U \subseteq \mathbb{R}$  is uniquely specified by its membership function  $\mu_i$ :  $U \rightarrow [0,1]$ . Thus, the fuzzy set is described as follows:

$$F = \{(u, \mu_{E}(u)) | u \in U\}$$
(1.1)

Two important concepts of *core* and *support* are related to a fuzzy set *F*:

$$core(F) = \{u \mid u \in U \land \mu_F(u) = 1\}$$

and

support 
$$(F) = \{u \mid u \in U \land \mu_F(u) > 0\}.$$

For our purpose, we use a trapezoidal membership function MF which is mathematically defined by four parameters  $\{a,b,c,d\}$ :

$$\operatorname{trap} \mathbf{mf}(u; a, b, c, d) = \begin{cases} \mathbf{0}, & u < a \\ u - a, & a \le u \le b \\ \mathbf{1}, & b \le u \le c \\ \frac{d - u}{d - c}, & c \le u \le d \\ \mathbf{0}, & d \le u \end{cases}$$
(1.2)

Let F and G be two fuzzy sets in the universe U, we say that  $F \subseteq G \Leftrightarrow \mu_F(u) \leq \mu_G(u)$ ,  $\forall u \in U$ . The complement of F, denoted by  $F^c$ , is defined by  $\mu_{F^c}(u) = 1 - \mu_F(u)$ . Furthermore,  $F \cap G$  (respectively  $F \cup G$ ) is defined the following way:  $\mu_{F \cap G} = \min(\mu_F(u), \mu_G(u))$  (respectively  $\mu_{F \cup G} = \max(\mu_F(u), \mu_G(u))$ ).

#### 1.2.2 Fuzzy Rule-Based Classifiers

We assume that we have an M-class pattern classification problem in an n-dimensional normalized hyper-cube  $[0, 1]^n$ . For this problem, we use fuzzy rules of the following type:

Rule 
$$R_q$$
: If  $x_1$  is  $A_{q1}$  and ... and  $x_n$  is  $A_{qn}$  then Class  $C_q$  with  $CF_q$ , (1.3)

where  $R_q$  is the label of the  $q^{th}$  fuzzy rule,  $\mathbf{x}=(x_1,...,x_n)$  is an n-dimensional pattern/feature vector,  $A_{qi}$  is an antecedent fuzzy set (i=1,...,n),  $C_q$  is a class label,

6 T. Jaworska

 $CF_q$  is a real number in the unit interval [0,1] which represents a rule weight. The rule weight can be specified by a heuristic manner or it can be adjusted by a learning algorithm [17], [18]. We use the *n*-dimensional fuzzy vector  $A_q = (A_{ql}, ..., A_{qn})$  to represent the antecedent part of the fuzzy rule  $R_q$  in (3) in a concise manner.

Let S be a set of fuzzy rules of the type in (3). That is, S is a fuzzy rule-based classifier. When an *n*-dimensional pattern/feature  $\mathbf{x}_p = (x_{p1}, ..., x_{pm})$  is presented to S, first the compatibility grade of  $\mathbf{x}_p$  with the antecedent part  $\mathbf{A}_q$  of each fuzzy rule  $\mathbf{R}_q$  in S is calculated by the product operator as

$$\mu_{\mathbf{A}q}(\mathbf{x}_p) = \mu_{\mathbf{A}q1}(\mathbf{x}_{p1}) \times \dots \times \mu_{\mathbf{A}qn}(\mathbf{x}_{pn}) \text{ for } R_q \in S, \tag{1.4}$$

where  $\mu_{\mathbf{A}qi}$  (.) shows the membership function of  $A_{qi}$ . Then a single winner rule  $R_{w(\mathbf{x}_p)}$  is identified for  $\mathbf{x}_p$  as follows:

$$CF_{w(\mathbf{x}^{p})} \times \mu_{\mathbf{A}_{w(\mathbf{x}^{p})}}(\mathbf{x}_{p}) = \max \{CF_{q} \times \mu_{\mathbf{A}q}(\mathbf{x}_{p}) \mid R_{q} \in S\}, \tag{1.5}$$

where  $w(\mathbf{x}_p)$  denotes the rule index of the winner rule for  $\mathbf{x}_p$ .

The pattern  $\mathbf{x}_p$  is classified by the single winner rule  $R_{w(\mathbf{x}_p)}$  as its consequent class. If there is no fuzzy rule with a positive compatibility grade with  $\mathbf{x}_p$  (i.e., if  $\mathbf{x}_p$  is not covered by any fuzzy rules in S), the classification of  $\mathbf{x}_p$  is rejected. The classification of  $\mathbf{x}_p$  is also rejected if multiple fuzzy rules with different consequent classes have the same maximum value on the right-hand side of (5). In this case,  $\mathbf{x}_p$  is exactly on the classification boundary between the different classes.

We use the single winner-based fuzzy reasoning method in (5) for pattern classification. This is because a responsible fuzzy rule can be always identified for the classification result of each input pattern when we use the single winner-based fuzzy reasoning method.

An ideal theoretical example of a simple three-class, two-dimensional pattern classification problem with 20 patterns from each class is considered in [19]. There three linguistic values (*small*, *medium* and *large*) were used as antecedent fuzzy sets for each of the two attributes and  $3\times3$  fuzzy rules were generated.  $S_1$  was the fuzzy rule-based classifier with the 9 fuzzy rules shown below:

#### $S_1$ : fuzzy rule-based classifier with 9 fuzzy rules

 $R_1$ : If  $x_1$  is *small* and  $x_2$  is *small* then Class2 with 1.0,  $R_2$ : If  $x_1$  is *small* and  $x_2$  is *medium* then Class2 with 1.0,  $R_3$ : If  $x_1$  is *small* and  $x_2$  is *large* then Class1 with 1.0,  $R_4$ : If  $x_1$  is *medium* and  $x_2$  is *small* then Class2 with 1.0,  $R_5$ : If  $x_1$  is *medium* and  $x_2$  is *medium* then Class2 with 1.0.

 $R_6$ : If  $x_1$  is *medium* and  $x_2$  is *large* then Class1 with 1.0,  $R_7$ : If  $x_1$  is *large* and  $x_2$  is *small* then Class3 with 1.0,  $R_8$ : If  $x_1$  is *large* and  $x_2$  is *medium* then Class3 with 1.0,  $R_9$ : If  $x_1$  is *large* and  $x_2$  is *large* then Class3 with 1.0,

$R_3$	$R_6$	$R_9$
$R_2$	$R_5$	$R_8$
$R_1$	$R_4$	$R_7$

**Fig. 1.1** Classification boundaries for fuzzy rule-based classifier \$1.

For simplicity, the rule weight is 1.0 in  $S_1$ . The location of each rule is shown in Fig. 1.1.

#### 1.3 Graphical Data Representation

In our system, Internet images are downloaded. Firstly, the new image is segmented, creating a collection of objects. Each object, selected according to the algorithm presented in detail in [21], is described by some low-level features. The features describing each object include: average colour  $k_{av}$ , texture parameters  $T_p$ , area A, convex area  $A_c$ , filled area  $A_p$ , centroid  $\{x_c, y_c\}$ , eccentricity e, orientation  $\alpha$ , moments of inertia  $m_{11}$ , bounding box  $\{bb_1(x,y), ..., bb_s(x,y)\}$  (s – number of vertices), major axis length  $m_{long}$ , minor axis length  $m_{short}$ , solidity s and Euler number E and Zernike moments  $Z_{00}, ..., Z_{33}$ . All features, as well as extracted images of graphical objects, are stored in the DB. Let Fo be a set of features where:

$$F_o = \{k_{av}, T_{p}, A, A_{c}, ..., E\}$$
 (1.6)

For ease of notation we will use  $F_o = \{f_1, f_2, ..., f_r\}$ , where r – number of attributes. For an object, we construct a feature vector O containing the above-mentioned features:

$$O = \begin{bmatrix} O(k_{av}) \\ O(T_p) \\ O(A) \\ \vdots \\ O(Z_{33}) \end{bmatrix} = \begin{bmatrix} O(f_1) \\ O(f_2) \\ O(f_3) \\ \vdots \\ O(f_r) \end{bmatrix}.$$

$$(1.7)$$

The next complex feature attributed to objects is texture. Texture parameters are found in the wavelet domain (the Haar wavelets are used). The algorithm details are also given in [21]. The use of this algorithm results in obtaining two ranges for the horizontal object dimension h and two others for the vertical one v:

$$T_{p} = \begin{cases} h_{\min_{1,2}}; h_{\max_{1,2}} \\ v_{\min_{1,2}}; v_{\max_{1,2}} \end{cases}$$
 (1.8)

Additional features of the low level for objects are shape descriptors. They are also included in the above-mentioned feature vector. We apply the two most important shape descriptors such as moments of inertia:

$$\mu_{pq} = \sum_{x} \sum_{y} (x - \overline{x})^{p} (y - \overline{y})^{q} f(x, y), \qquad p, q = 0, 1, 2$$
(1.9)

and Zernike moments [20]. Zernike moments are a set of complex polynomials  $\{V_{pq}(x,y)\}$  which form a complete orthogonal set over the unit disk of  $x^2 + y^2 \le 1$ . Hence, the definition of 2D Zernike moments with  $p^{th}$  order with repetition q for intensity function f(x,y) of the image is described as:

$$Z_{pq} = \frac{p+1}{\pi} \iint_{x^2 + y^2 \le 1} V_{pq}^*(x, y) f(x, y) dxdy$$
 (1.10)

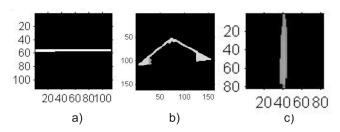
8 T. Jaworska

where: 
$$V_{pq}^{*}(x, y) = V_{p,-q}(x, y)$$
. (1.11)

For our purpose, the first 10 Zernike moments are sufficient, which means we calculate moments from  $Z_{00}$  to  $Z_{33}$ .

#### 1.4 Classification Results

The feature vector  $\mathbf{O}$  (cf. (7)) is used here as a pattern/feature vector  $\mathbf{x}$  for object classification. We collected n=32 features for each graphical object. Based on the data collected in our CBIR system, we have analysed the most distinguished features to present our experimental results. We have chosen three classes from graphical objects in the training subset, namely: class1 - horizontal line, class2 - caret and class3 - vertical line, presented respectively in Fig. 1.2.



**Fig. 1.2** Examples of graphical objects used as class1 - horizontal line a), class2 - caret b) and class3 - vertical line c) from the training subset.

For our fuzzy rule-based classifier we have chosen a trapezoidal MF (cf. (1.2)), as it better represents the character of our data. We have classified data from a training subset according to the fuzzy rule-based classifier  $S_1$ . As we mentioned earlier, in our experiment we used a three-class problem for two features:  $x_1$  – area and  $x_2$  – minor axis length (shown in Fig. 1.3).

Thanks to the use of the fuzzy rule-based classifier  $S_1$ , we can classify a new object (depicted as a magenta square in Fig. 1.4) from unknown class? to class2. After a comparison with the real image object, we can conclude that the classified object, in fact, belongs to class2. This confirms that we can use the single winner-based fuzzy reasoning method for our pattern classification (see Fig. 1.4).

In a multi-objective fuzzy rule-based classifier design, the accuracy of classifiers is not viewed as a factor related to interpretability. This is because accuracy is handled as a separate goal from interpretability in a multi-objective fuzzy rule-based classifier design. However, the accuracy of the winner rule seems to be an important factor, related to the explanation capacity for fuzzy rule-based classifiers [19].

Now, we show the use of a fuzzy rule-based classifier with three rules for our three-class problem, where:

#### S<sub>2</sub>: fuzzy rule-based classifier with three fuzzy rules [19]

 $R_{123}$ : If  $x_1$  is *small* then Class 2 with 1.0,

 $R_{456}$ : If  $x_1$  is medium then Class2 with 1.0,

 $R_{789}$ : If  $x_1$  is *large* then Class3 with 1.0,

For this purpose we have chosen the fuzzy rule-based classifier  $S_2$ . As we have mentioned earlier, in our second experiment we used a three-class problem for two features:  $x_1$  – minor axis length and  $x_2$  – Zernike moment  $Z_{00}$ . We used a trapezoidal MF because the data are not normalised to the interval [0,1], according to the assumption from the fuzzy rules definition. We use the same classes (class1 – horizontal line, class2 – caret and class3 – vertical line). As it is shown in Fig. 1.5, the three rules are enough to separate the objects described by real data.

Through the use of the fuzzy rule-based classifier  $S_2$ , we can classify a new object (depicted as a magenta square in Fig. 1.6) from unknown class? to class2. After a comparison with the real image object, we can conclude that the classified object in fact belongs to class2. This confirms that we can use a single winner-based fuzzy reasoning method for our pattern classification (see Fig. 1.6).

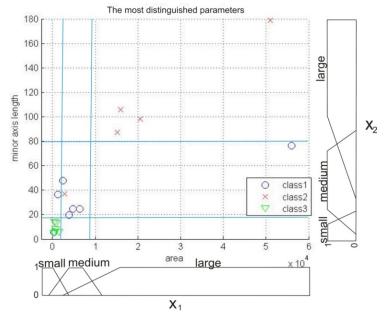


Fig. 1.3 Three-class problem for two features: x1 - minor axis length and x2 - area.

T. Jaworska

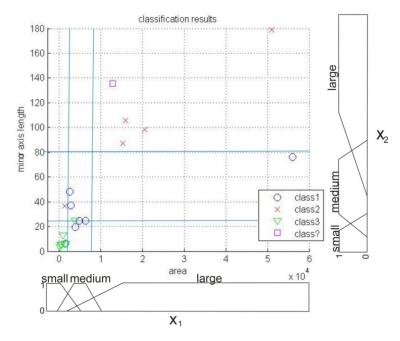


Fig. 1.4 The magenta square is a classified element for the fuzzy rule classifier S1 with 9 rules.

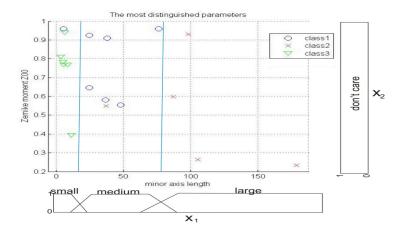


Fig. 1.5 Classification with three fuzzy rules S2

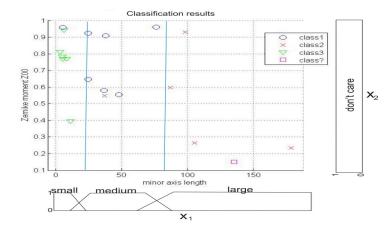


Fig. 1.6 Classification results for a classifier with three fuzzy rules S2

#### 1.5 Further Use of Classified Objects in CBIR

Therefore, we have to classify objects in order to [21]:

- use particular classes as patterns. We store these data in DB to use them in CBIR algorithms.
- specify a spatial object location in our system. In our system spatial object location in an image is used as the global feature. The object's mutual spatial relationship is calculated based on the algorithm adopted from the concept of principal component analysis (PCA), proposed by Chang and Wu [14] and later modified by Guru and Punitha [15], to determine the first principal component vectors (PCVs).
- 3. to help the user ask a query in GUI. The user chooses for a query graphical objects semantically collected in groups.
- 4. compare image objects coming from the same class as a stage in the image retrieval process. Let a query be an image  $I_q$ , such as  $I_q = \{o_{q1}, o_{q2}, ..., o_{qn}\}$ . An image in the database will be denoted as  $I_b$ ,  $I_b = \{o_{b1}, o_{b2}, ..., o_{bm}\}$ . In order to answer the query, represented by  $I_q$ , we compare it with each image  $I_b$  in DB. We determine the similarity between vectors of their signatures. Next, we find the spatial similarity between their PCVs. Later, we proceed to the final step, namely, we compare the similarity of the objects representing both images  $I_q$  and  $I_b$ , respectively between objects of the same class.

#### 1.6 Conclusions

In this chapter, first we have determined the ability of fuzzy sets and fuzzy rulebased classifiers to classify graphical objects in our CBIR system. We have shown an example of classification based on nine and three fuzzy rules according to the